

This is a personal TLDR of the following paper  
 Discovering faster matrix multiplication algorithms with RL - Deepmind

The crux of the paper is a perspective shift on matrix multiplications

$$\text{Ex. } \begin{pmatrix} a_1 & a_2 \\ a_3 & a_4 \end{pmatrix} \begin{pmatrix} b_1 & b_2 \\ b_3 & b_4 \end{pmatrix} = \begin{pmatrix} c_1 & c_2 \\ c_3 & c_4 \end{pmatrix}$$

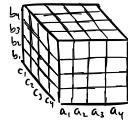
$$\text{now clearly } c_1 = a_1 b_1 + a_2 b_3 \quad \textcircled{1}$$

$$\vdots$$

$$c_4 = a_3 b_2 + a_4 b_4$$

The authors represent the eqn  $\textcircled{1}$  as a binary tensor  $T_n$

$T_{2x2}$  where the cell at  $(a_i, b_j, c_k)$  is 1 if  $c_k = a_i b_j + \dots$   
 0 otherwise



For example, in the  $2 \times 2$  case above,

$$\begin{array}{c|cc|cc|cc|cc} & & & & & & & \\ \hline & a_1 & a_2 & a_3 & a_4 & b_1 & b_2 & b_3 & b_4 \\ \hline c_1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ c_2 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ c_3 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\ c_4 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ \hline \end{array}$$

Now the cool part of their algo is through finding decompositions of  $T_n$ , they implicitly find diff procedures to perform the mat mul.

$$T_n = \sum_{r=1}^R u^{(r)} \otimes v^{(r)} \otimes w^{(r)}$$

$\hookrightarrow$  This is similar to SVD of  $A^{n \times n}$  but here we are doing it for  $A^{n \times n \times n}$ .

So imagine  $U, V, W \in \{-1, 0, 1\}^{n \times R}$  are given, how do you use them?

$$T_n = u^{(1)} \otimes v^{(1)} \otimes w^{(1)} + \dots \text{ geometrically } \begin{array}{c} \text{a stack of } n \text{ rectangles} \\ \text{with dimensions } u^{(1)}, v^{(1)}, w^{(1)} \end{array} \text{ therefore, } u^{(1)} \text{ correspond to } a \\ v^{(1)} \text{ correspond to } b \\ w^{(1)} \text{ correspond to } c$$

Thus the algo to actually perform mat mul given  $U, V, W$  is

Algo 1

```
for r=1 to R do
    m_r ← (u(r)a1 + ... + u(r)an) (v(r)b1 + ... + v(r)bn)
for i=1, ..., n2 do
    Ci ← w(1)m1 + ... + w(R)mR
return C
```

The RL agent has to find  $U, V, W$  and the authors construct a game, which is Let  $S_0 = T_n$ , the agent outputs  $(u^{(1)}, v^{(1)}, w^{(1)})$ , thus  $S_1 = S_0 - u^{(1)} \otimes v^{(1)} \otimes w^{(1)}$  and so on until  $S_R = 0$ . The agent is penalized for each step to encourage it to find shortest path (minimize R). The RL algo is based on AlphaZero where they do MCTS with a policy and value network.